## Kinematic factor derivation

Presented here is a full derivation of the kinematic factor using in ion scattering. Figure 1 shows a schematic of the binary collision model used in ion scattering.



Figure 1: Schematic demonstration of an ion scattering from a surface atom. An ion with mass  $m_1$  and kinetic energy  $E_0$  (velocity  $v_0$ ) is incident at an angle  $\alpha$  on a target atom with mass  $m_2$ . The ion is scattered through an angle  $\theta$  with respect to the incident direction, losing kinetic energy to the target atom during the collision. The scattered ion possesses a kinetic energy  $E_1$  (velocity  $v_1$ ), whilst the target atom recoils with a kinetic energy  $E_2$  (velocity  $v_2$ ) at an angle  $\phi$  with respect to the incident direction.

Conservation of energy gives:

$$m_1 v_0^2 = m_1 v_1^2 + m_2 v_2^2 \tag{1}$$

Rearranging this equation leads to:

$$v_2^2 = m_1(v_0^2 - v_1^2)$$
(2)

Conservation of momentum parallel to the incident direction can be expressed by:

$$m_1 v_0 = m_1 v_1 \cos \theta + m_2 v_2 \cos \phi \tag{3}$$

This can be rearranged and squared to give:

$$m_1^2 v_0^2 + m_1^2 v_1^2 \cos^2 \theta - 2m_1^2 v_0 v_1 \cos \theta = m_2^2 v_2^2 \cos^2 \phi$$
(4)

Momentum perpendicular to the incident direction is given by:

$$0 = m_1 v_1 \sin \theta - m_2 v_2 \sin \phi \tag{5}$$

Rearranging this equation and squaring gives:

$$m_1^2 v_1^2 \sin^2 \theta = m_2^2 v_2^2 \sin^2 \phi$$
 (6)

Adding equations 4 and 6 gives:

$$m_1^2 v_0^2 + m_1^2 v_1^2 (\cos^2 \theta + \sin^2 \theta) - 2m_1^2 v_0 v_1 \cos \theta = m_2^2 v_2^2 (\cos^2 \phi + \sin^2 \phi)$$
 (7)

Recognising that  $\cos^2 \theta + \sin^2 \theta = 1$  leads to:

$$m_1^2 v_0^2 + m_1^2 v_1^2 - 2m_1^2 v_0 v_1 \cos \theta = m_2^2 v_2^2$$
(8)

Substituting equation 2 into the right hand side of equation 8 gives:

$$m_1^2 v_0^2 + m_1^2 v_1^2 - 2m_1^2 v_0 v_1 \cos \theta = m_2 m_1 (v_0^2 - v_1^2)$$
(9)

Dividing both sides by  $m_1^2 v_0^2 \ {\rm gives:}$ 

$$1 + \frac{v_1^2}{v_0^2} - \frac{2v_1\cos\theta}{v_0} = \frac{m_2}{m_1}(1 - \frac{v_1^2}{v_0^2})$$
(10)

Setting  $m_2/m_1 = A$  and rearranging gives:

$$\frac{v_1^2}{v_0^2}(1+A) - \frac{2v_1\cos\theta}{v_0} + (1-A) = 0$$
(11)

This is a quadratic in  $v_1/v_0$ . Using the quadratic formula:

$$X = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \tag{12}$$

with X =  $v_1/v_0$ , a = (1 + A), b =  $2\cos heta$  and c = (1 - A) leads to:

$$\frac{v_1}{v_0} = \frac{2\cos\theta \pm \sqrt{4\cos^2\theta - 4(1+A)(1-A)}}{2(1+A)}$$
(13)

This reduces to:

$$\frac{v_1}{v_0} = \frac{\cos\theta \pm \sqrt{\cos^2\theta - (1+A)(1-A)}}{(1+A)}$$
(14)

Multiplying out the terms included in the square root gives:

$$\frac{v_1}{v_0} = \frac{\cos\theta \pm \sqrt{A^2 + \cos^2\theta - 1}}{(1+A)}$$
(15)

However,  $cos^2\theta$  - 1 = -  $sin^2\theta$ , so:

$$\frac{v_1}{v_0} = \frac{\cos\theta \pm \sqrt{A^2 - \sin^2\theta}}{(1+A)} \tag{16}$$

As the kinematic factor,  $k=\mathsf{E}_1$  /  $\mathsf{E}_0=m_1v_1^2$  /  $m_1v_0^2$  , then:

$$k = \frac{E_1}{E_0} = \frac{1}{(1+A)^2} (\cos\theta \pm \sqrt{A^2 - \sin^2\theta})^2$$
(17)

For CAICISS,  $\theta = 180^{\circ}$ , so:

$$k = \frac{(A-1)^2}{(A+1)^2}$$
(18)